NAG Fortran Library Routine Document

F11XAF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

F11XAF computes a matrix-vector or transposed matrix-vector product involving a real sparse nonsymmetric matrix stored in coordinate storage format.

2 Specification

```
SUBROUTINE F11XAF(TRANS, N, NNZ, A, IROW, ICOL, CHECK, X, Y, IFAIL)

INTEGER N, NNZ, IROW(NNZ), ICOL(NNZ), IFAIL

real A(NNZ), X(N), Y(N)

CHARACTER*1 TRANS, CHECK
```

3 Description

F11XAF computes either the matrix-vector product y = Ax, or the transposed matrix-vector product $y = A^Tx$, according to the value of the argument TRANS, where A is an n by n sparse nonsymmetric matrix, of arbitrary sparsity pattern. The matrix A is stored in coordinate storage (CS) format (see Section 2.1.1 of the F11 Chapter Introduction). The array A stores all non-zero elements of A, while arrays IROW and ICOL store the corresponding row and column indices respectively.

It is envisaged that a common use of F11XAF will be to compute the matrix-vector product required in the application of F11BEF to sparse linear systems. An illustration of this usage appears in Section 9 of the routine document for F11DDF.

4 References

None.

5 Parameters

1: TRANS – CHARACTER*1

Input

On entry: specifies whether or not the matrix A is transposed:

```
if TRANS = 'N', then y = Ax is computed;
if TRANS = 'T', then y = A^{T}x is computed.
```

Constraint: TRANS = 'N' or 'T'.

2: N – INTEGER

Input

On entry: n, the order of the matrix A.

Constraint: $N \ge 1$.

3: NNZ – INTEGER

Input

On entry: the number of non-zero elements in the matrix A.

Constraint: $1 \leq NNZ \leq N^2$.

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4: A(NNZ) - real array

Input

On entry: the non-zero elements in the matrix A, ordered by increasing row index, and by increasing column index within each row. Multiple entries for the same row and column indices are not permitted. The routine F11ZAF may be used to order the elements in this way.

5: IROW(NNZ) – INTEGER array

Input

6: ICOL(NNZ) - INTEGER array

Input

On entry: the row and column indices of the non-zero elements supplied in A.

Constraints: IROW and ICOL must satisfy the following constraints (which may be imposed by a call to F11ZAF):

```
1 \leq IROW(i) \leq N, 1 \leq ICOL(i) \leq N, for i = 1, 2, ..., NNZ.
```

$$IROW(i-1) < IROW(i)$$
, or $IROW(i-1) = IROW(i)$ and $ICOL(i-1) < ICOL(i)$, for $i = 2, 3, ..., NNZ$.

7: CHECK – CHARACTER*1

Input

On entry: specifies whether or not the CS representation of the matrix A should be checked:

if CHECK = 'C', checks are carried on the values of N, NNZ, IROW and ICOL;

if CHECK = 'N', none of these checks are carried out.

See also Section 8.2.

Constraint: CHECK = 'C' or 'N'.

8: X(N) - real array

Input

On entry: the vector x.

9: Y(N) - real array

Output

On exit: the vector y.

10: IFAIL - INTEGER

Input/Output

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

```
On entry, TRANS \neq 'N' or 'T', or CHECK \neq 'C' or 'N'.
```

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```
\begin{aligned} \text{IFAIL} &= 2 \\ &\quad \text{On entry, } N < 1, \\ &\quad \text{or } &\quad \text{NNZ} < 1, \\ &\quad \text{or } &\quad \text{NNZ} > N^2. \end{aligned}
```

IFAIL = 3

On entry, the arrays IROW and ICOL fail to satisfy the following constraints:

```
1 \leq \text{IROW}(i) \leq \text{N} and 1 \leq \text{ICOL}(i) \leq \text{N}, for i = 1, 2, \dots, \text{NNZ}; \text{IROW}(i-1) < \text{IROW}(i), or \text{IROW}(i-1) = \text{IROW}(i) and \text{ICOL}(i-1) < \text{ICOL}(i), for i = 2, 3, \dots, \text{NNZ}.
```

Therefore a non-zero element has been supplied which does not lie within the matrix A, is out of order, or has duplicate row and column indices. Call F11ZAF to reorder and sum or remove duplicates.

7 Accuracy

The computed vector y satisfies the error bound:

$$\|y - Ax\|_{\infty} \le c(n)\epsilon \|A\|_{\infty} \|x\|_{\infty}$$
, if TRANS = 'N', or $\|y - A^Tx\|_{\infty} \le c(n)\epsilon \|A^T\|_{\infty} \|x\|_{\infty}$, if TRANS = 'T',

where c(n) is a modest linear function of n, and ϵ is the **machine precision**.

8 Further Comments

8.1 Timing

The time taken for a call to F11XAF is proportional to NNZ.

8.2 Use of CHECK

It is expected that a common use of F11XAF will be to compute the matrix-vector product required in the application of F11BEF to sparse linear systems. In this situation F11XAF is likely to be called many times with the same matrix A. In the interests of both reliability and efficiency you are recommended to set CHECK to 'C' for the first of such calls, and to 'N' for all subsequent calls.

9 Example

This example program reads in a sparse matrix A and a vector x. It then calls F11XAF to compute the matrix-vector product y = Ax and the transposed matrix-vector product $y = A^Tx$.

9.1 Program Text

Note: the listing of the example program presented below uses **bold italicised** terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
F11XAF Example Program Text
Mark 20 Revised. NAG Copyright 2001.
.. Parameters ..
INTEGER
                 NIN, NOUT
PARAMETER
                 (NIN=5, NOUT=6)
INTEGER
                 LA, NMAX
PARAMETER
                 (LA=10000,NMAX=1000)
.. Local Scalars ..
                 I, IFAIL, N, NNZ
INTEGER
CHARACTER
                 CHECK, TRANS
.. Local Arrays .
                 A(LA), X(NMAX), Y(NMAX)
```

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```
INTEGER
                   ICOL(LA), IROW(LA)
   .. External Subroutines ..
  EXTERNAL
                   F11XAF
   .. Executable Statements ..
  WRITE (NOUT,*) 'F11XAF Example Program Results'
  Skip heading in data file
  READ (NIN, *)
  Read order of matrix and number of non-zero entries
  READ (NIN,*) N
  IF (N.LE.NMAX) THEN
     READ (NIN,*) NNZ
     Read the matrix A
      DO 20 I = 1, NNZ
        READ (NIN,*) A(I), IROW(I), ICOL(I)
      CONTINUE
20
     Read the vector x
      READ (NIN, *) (X(I), I=1, N)
      Calculate matrix-vector product
      TRANS = 'N'
      CHECK = 'C'
      IFAIL = 0
      CALL F11XAF(TRANS, N, NNZ, A, IROW, ICOL, CHECK, X, Y, IFAIL)
      Output results
      WRITE (NOUT, *)
      WRITE (NOUT,*) ' Matrix-vector product'
      DO 40 I = 1, N
        WRITE (NOUT, '(D16.4)') Y(I)
40
      CONTINUE
      Calculate transposed matrix-vector product
      TRANS = 'T'
      CHECK = 'N'
      IFAIL = 0
      CALL F11XAF(TRANS, N, NNZ, A, IROW, ICOL, CHECK, X, Y, IFAIL)
      Output results
      WRITE (NOUT, *)
      WRITE (NOUT, \star) ' Transposed matrix-vector product'
      DO 60 I = 1, N
         WRITE (NOUT, '(D16.4)') Y(I)
60
     CONTINUE
  END IF
  STOP
  END
```

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9.2 Program Data

```
F11XAF Example Program Data
11
                     NNZ
 2.
 1.
      1
           2
      2
 1.
           3
-1.
      2
           4
 4.
      3
           1
 1.
      3
           3
 1.
      3
           5
 1.
      4
           4
 2.
      4
           5
-2.
      5
      5
                     A(I), IROW(I), ICOL(I), I=1,...,NNZ
 3.
           5
0.70 0.16 0.52
0.77 0.28
                     X(I), I=1,...,N
```

9.3 Program Results

0.2900E+01

```
F11XAF Example Program Results
```

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